# BIFURCATION OF PERIODIC SOLUTIONS IN A NONLINEAR DIFFERENCE-DIFFERENTIAL EQUATION OF NEUTRAL TYPE* 

BY<br>ROBERT K. BRAYTON<br>IBM Watson Research Center, Yorktown Heights, New York


#### Abstract

The existence of a self-sustained periodic solution in the autonomous equation $$
u^{\prime}(\tau)-\alpha u^{\prime}(\tau-h)+\beta u(\tau)+\alpha \gamma u(\tau-h)=\epsilon f(u(\tau))
$$ is proved under appropriate assumptions on $\alpha, \beta, \gamma, f$ and $h$. The method of proof consists in converting this equation into an equivalent nonlinear integral equation and demonstrating the convergence of an appropriate iteration scheme.


In this paper we consider the equation

$$
\begin{equation*}
u^{\prime}(\tau)-\alpha u^{\prime}(\tau-h)+\beta u(\tau)+\alpha \gamma u(\tau-h)=\epsilon f(u(\tau)) \tag{1}
\end{equation*}
$$

where $h \geq 0$ and $\alpha=\alpha_{0}(1+\epsilon)$. The existence of a periodic solution will be proved for small $\epsilon \geq 0$ under appropriate assumptions on the parameters $\alpha_{0}, \beta, \gamma$, and $f$. The left-hand side of this equation is a linear difference-differential operator of neutral type (for a definition see [1]). The existence of periodic solutions for functional-differential equations which include difference-differential equations of retarded type but not neutral type has been discussed by Krasovskii [2], Shimanov [3], [4], and Hale [5]. In all these cases, the equations are of the forced type where the right-hand side is a $2 \pi$-periodic function of $\tau$. Equation (1), which we consider, is autonomous, and we look for a self-sustained oscillation.

Difference-differential equations of the type (1) arise from electrical networks such as the one shown in Fig. 1. The equations of this network are

$$
\begin{align*}
L(\partial i / \partial t) & =-\partial v / \partial x, \quad 0 \leq x \leq 1  \tag{2}\\
C(\partial v / \partial t) & =-\partial i / \partial x, \\
E-v(0, t)-R i(0, t)= & 0, \quad C_{1}(d v(1, t) / d t)=i(1, t)-g(v(1, t))
\end{align*}
$$

where $L, C$ are the specific inductance and capacitance in the transmission line. The question of the existence of a periodic solution of some unknown period $T$ can be posed by giving the additional boundary conditions

$$
v(x, 0)=v(x, T), \quad i(x, 0)=i(x, T)
$$

Thus, we have a boundary-value problem for a hyperbolic partial differential equation with boundary conditions given on the rectangle shown in Fig. 2. Of course, in general, a boundary-value problem for a hyperbolic equation is not well posed. The difference here is that the boundary $t=T$ is free to be chosen.

[^0]

Fig. 1. Transmission Line Network

As described in [6], Eqs. (2) can be written in the form
$C\left(v^{\prime}(t)+K v^{\prime}(t-h)\right)+\left(1 / z-g^{*}\right) v(t)-K\left(1 / z+g^{*}\right) v(t-h)=f(v(t), v(t-h))$,
where $K=(R-z) /(R+z), z=(L / C)^{1 / 2}, h=2(L C)^{1 / 2}, f(v, w)=O\left(v^{3}+w^{3}\right)$ and $g^{*}$ is the derivative of $g(v)$ at some point $v=v_{0}$. Clearly, Eq. (3) can be brought into the form of Eq. (1) with the transformation $v=\epsilon^{1 / 2} u$ except for the fact that $f$ depends on $v(t-h)$. However, in what follows, there is no essential difficulty in handling this case, and for simplicity we neglect this generalization.

In Eq. (1), let $t=\omega \tau$ where $\omega$ is unknown, and let us seek a periodic solution of period $2 \pi$ in $t$. With $v(t)=u(\tau)$ Eq. (1) becomes

$$
\begin{equation*}
L_{\epsilon}[v] \equiv \omega\left(v^{\prime}(t)-\alpha v^{\prime}(t-\omega h)\right)+\beta v(t)+\alpha \gamma v(t-\omega h)=\epsilon f(v(t)) \tag{4}
\end{equation*}
$$

The linear operator $L_{\epsilon}$ is a difference-differential operator of neutral type and, as we shall see, the parameter $\alpha_{0}$ appearing in $\alpha=\alpha_{0}(1+\epsilon)$ will be chosen so that there exists exactly one pair of purely imaginary characteristic roots of $L_{0}$.

The characteristic equation associated with the operator $L_{6}$ is

$$
\begin{equation*}
q(s \omega) \equiv s \omega(1-\alpha \exp (-s \omega h))+\beta+\alpha \gamma \exp (-s \omega h)=0 \tag{5}
\end{equation*}
$$

where $s$ is a complex number. We shall prove the existence of periodic solutions of (4) for $\epsilon$ small under the condition that for $\alpha=\alpha_{0}$ Eq. (5) has roots $s \omega= \pm i \omega_{0}$. First, we prove the following

Lemma 1. For $\gamma>\beta>0$ there exists an infinite set of real pairs ( $\alpha_{0}, \omega_{0}$ ) such that

$$
\begin{equation*}
i \omega_{0}\left(1-\alpha_{0} \exp \left(-i \omega_{0} h\right)\right)+\beta+\alpha_{0} \gamma \exp \left(-i \omega_{0} h\right)=0 \tag{5a}
\end{equation*}
$$

where $\alpha_{0}^{2}<1$.
Proof: By writing (5a) in its real and imaginary parts and solving for $\sin \omega_{0} h$,


Fig. 2. Periodic Cell
$\cos \omega_{0} h$, we find

$$
\begin{align*}
& \sin \omega_{0} h=\frac{\omega_{0}}{\alpha_{0}} \frac{\gamma+\beta}{\omega_{0}^{2}+\gamma^{2}},  \tag{6}\\
& \cos \omega_{0} h=\frac{1}{\alpha_{0}} \frac{\omega_{0}^{2}+\gamma \beta}{\omega_{0}^{2}+\gamma^{2}}, \tag{7}
\end{align*}
$$

which can be combined to yield

$$
\begin{gather*}
\omega_{0}^{2}=\frac{\alpha_{0}^{2} \gamma^{2}-\beta^{2}}{1-\alpha_{0}^{2}}  \tag{8}\\
\tan \omega_{0} h=\frac{\omega_{0}(\gamma+\beta)}{\omega_{0}^{2}-\gamma \beta} \tag{9}
\end{gather*}
$$

The solutions of Eq. (9), which is independent of $\alpha_{0}$, can be found graphically as shown in Fig. 3. Clearly for any $\omega_{0}$ satisfying (9), there exists an $\alpha_{0}^{2}$ such that (8) holds because $\left(\alpha_{0}^{2} \gamma^{2}-\beta^{2}\right) /\left(1-\alpha_{0}^{2}\right)$ can be made to range between $-\beta^{2}$ and $+\infty$ by varying $\alpha_{0}^{2}$ between 0 and 1. Eqs. (8) and (9) give pairs $\omega_{0}, \alpha_{0}^{2}$ and by taking the correct sign on $\alpha_{0}$, the pairs $\omega_{0}, \alpha_{0}$ satisfy (5a). Arranging the $\omega_{0}$ in increasing order starting with $\omega_{0}=0$ the corresponding $\alpha_{0}$ alternate in sign starting with $\alpha_{0}=-\beta / \gamma$.

Note that for $\alpha=0$, there is only one root of (5), namely $s \omega=-\beta<0$. As $\alpha^{2}$ is increased, there is an infinity of roots which all lie in the left-half $s \omega$ plane. When $\alpha=-\beta / \gamma$, we have the first root crossing the imaginary axis at $s \omega=0$. Similarly, when $\alpha$ equals the first positive $\alpha_{0}$, we have a pair of roots $s \omega= \pm i \omega_{0}$ crossing the imaginary axis. The remainder of the roots of (5) lie in the left-half plane because of continuity with respect to $\alpha$. For all other pairs $\alpha_{0}$, $\omega_{0}$ there is at least one root in the right half-plane. For this reason we expect that the periodic solution associated with the pair $\alpha_{0}, \omega_{0}$ corresponding to the first positive value of $\alpha_{0}$ is the only stable periodic solution.

However, since existence and stability are independent concepts, the following theorem is applicable for any solution $\alpha_{0}, \omega_{0}$ of (5a). The theorem states the existence of a periodic solution* near the function $v=2 a^{*}$ cost where $a^{*}$ satisfies the bifurcation equation


Fig. 3. Graphical Solution of Equation (9)

[^1]\[

$$
\begin{equation*}
a^{*}=\frac{1}{2 \pi x_{0}} \int_{0}^{2 \pi} f\left(2 a^{*} \cos t\right) \cos t d t \tag{10}
\end{equation*}
$$

\]

and $x_{0}$ is specified by (12) below. If $a^{*}=0$, the theorem is trivial, and therefore, we rule this out. An example of a nonlinear function $f$ where there is a nonzero solution of $(10)$ is $f(v)=-v^{3}$. Then the solution is a $a^{*}=\left[-x_{0} / 3\right]^{1 / 2}$ which is real since it is shown below that $x_{0}<0$.

Theorem. Let $\left(\alpha_{0}, \omega_{0}\right)$ be any pair satisfying (5a) where $\omega_{0} \neq 0$ and assume that there exists a real solution $a^{*} \neq 0$ of

$$
F\left(a^{*}\right) \equiv a^{*}-\frac{1}{2 \pi x_{0}} \int_{0}^{2 \pi} f\left(2 a^{*} \cos t\right) \cos t d t=0
$$

such that $|\partial F / \partial a|_{a=a^{*}} \geq \mu>0$ where $x_{0}$ is specified by (12) below. Also assume that $f$ is continuously differentiable, $f(0)=f^{\prime}(0)=0$, and $\left|f^{\prime}(v)\right|<\nu$ for $|v|<4\left|a^{*}\right|$. Then for small $\epsilon \geq 0$, there exist functions $\omega=\omega(\epsilon), v=v(t, \epsilon)$ such that $v(t, \epsilon)$ is a $2 \pi$-periodic solution of (4) with $\omega=\omega(\epsilon)$. Furthermore, $\omega(0)=\omega_{0}$ and $v(t, 0)=2 a^{*} \cos t$.

Note. For $\epsilon=0$, a two-parameter family of periodic solutions exists of the form $v=a e^{i t}+\bar{a} e^{-i t}$ where $a$ is an arbitrary complex number. This follows since (5a) implies that $L_{0}\left[e^{ \pm i t}\right]=0$. However, since the equation is autonomous, this family is a oneparameter family modulo an arbitrary translation of time. We represent this family by $v(t)=2 a \cos t$ where $a$ is an arbitrary real number. The above theorem implies that as $\epsilon$ becomes positive the solution $v(t)=2 a^{*} \cos t$ bifurcates into a neighboring periodic solution with period in the $\tau$ variable equal to $2 \pi / \omega(\epsilon)$.

Proof of Theorem: The first part of the proof will be to transform Eq. (4) into an integral equation. For this purpose we make the following definition

$$
q_{\epsilon}(i k) \equiv \exp (-i k t) L_{\epsilon}[\exp (i k t)]
$$

and establish some properties of $q_{\epsilon}(i k)$. Clearly from (4) or (5),

$$
\begin{equation*}
q_{\epsilon}(i k)=i k \omega(1-\alpha \exp (-i k \omega h))+\beta+\alpha \gamma \exp (-i k \omega h) \tag{11}
\end{equation*}
$$

where $\alpha=\alpha_{0}(1+\epsilon)$ and $\omega=\omega(\epsilon)$ is an unspecified function of $\epsilon$. If $\left(\alpha_{0}, \omega(0)\right)$ is a pair satisfying (5a), then

$$
q_{0}( \pm i)=0
$$

Let $\omega=\omega_{0}+\epsilon \omega_{1}$ and define $x\left(\omega_{1}, \epsilon\right)+i y\left(\omega_{1}, \epsilon\right) \equiv q_{\epsilon}(i) / \epsilon$. Now $x$ is bounded away from zero if $\epsilon$ is small enough and $\omega_{1} \geq 0$. This follows since
$x_{0} \equiv \lim _{\epsilon \rightarrow 0} x\left(\omega_{1}, \epsilon\right)=\omega_{1}\left(-\alpha_{0} \sin \omega_{0} h-\alpha_{0} \omega_{0} h \cos \omega_{0} h-\alpha_{0} \gamma h \sin \omega_{0} h\right)$

$$
+\alpha_{0} \gamma \cos \omega_{0} h-\alpha_{0} \omega_{0} \sin \omega_{0} h
$$

Using (6) and (7) this becomes

$$
\begin{equation*}
x_{0}=\omega_{1}\left[\frac{-\omega_{0}\left(\gamma+\beta+h\left(\omega_{0}^{2}+\gamma^{2}\right)\right)}{\omega_{0}^{2}+\gamma^{2}}\right]-\beta \tag{12}
\end{equation*}
$$

Hence, if $0 \leq \omega_{1}$, then $x_{0}<-\beta$ and by continuity $x\left(\omega_{1}, \epsilon\right) \leq-\beta / 2$ for $\epsilon$ small. For future reference we compute

$$
\begin{align*}
y_{0} \equiv \lim _{\epsilon \rightarrow 0} y\left(\omega_{1}, \epsilon\right)= & \omega_{1}\left[1-\alpha_{0} \cos \omega_{0} h-\alpha_{0} \gamma h \cos \omega_{0} h+\alpha_{0} \omega_{0} h \sin \omega_{0} h\right] \\
& -\alpha_{0} \gamma \sin \omega_{0} h-\alpha_{0} \omega_{0} \cos \omega_{0} h \\
= & \omega_{1}\left[\frac{\gamma(\gamma+\beta)+h \beta\left(\gamma^{2}+\omega_{0}^{2}\right)}{\omega_{0}^{2}+\gamma^{2}}\right]-\omega_{0} \tag{13}
\end{align*}
$$

which, we note, can be zero for $\omega_{1}>0$.
In addition, we note that $\left|q_{\epsilon}(i k)\right| \geq \eta>0$ for $k \neq \pm 1$ and $\epsilon$ small. For if $\lim _{n \rightarrow \infty}\left|q_{\epsilon}\left(i k_{n}\right)\right|=0, k_{n} \neq \pm 1$, then for $n \geq N(\epsilon)$

$$
k_{n}^{2} \omega^{2}=\frac{\alpha^{2} \gamma^{2}-\beta^{2}}{1-\alpha^{2}}+O(\epsilon) .
$$

But $\left(\alpha^{2} \gamma^{2}-\beta^{2}\right) /\left(1-\alpha^{2}\right)=\omega_{0}^{2}+O(\epsilon)$ and, therefore,

$$
k_{n}^{2}\left(\omega_{0}+\epsilon \omega_{1}\right)^{2}=\omega_{0}^{2}+O(\epsilon), \quad k_{n} \neq \pm 1
$$

which is impossible if $\epsilon$ is small.
Now we want to show that if $v(t)$ is a periodic solution of (4), then it is necessary and sufficient that $v(t)$ is an $H_{1}^{*}$ solution of the following nonlinear integral equation

$$
\begin{equation*}
v(t)=\frac{1}{2 \pi} \int_{0}^{2 \pi} K^{*}(t-s) f(v(s)) d s \tag{14}
\end{equation*}
$$

where

$$
\begin{equation*}
K^{*}(t-s)=\sum_{k} \frac{\epsilon \exp (i k(t-s))}{q_{\epsilon}(i k)} \tag{15}
\end{equation*}
$$

We note that Eq. (14) has a free parameter $\omega_{1}$ occurring in $q_{\epsilon}(i k)$.
To show necessity, let $v(t)$ be a real periodic solution of (4). Then $v$ and $f(v)$ (since $f$ is differentiable) have Fourier expansions

$$
\begin{aligned}
v & =\sum_{k} v_{k} e^{i k t} \\
f(v) & =\sum_{k} f_{k} e^{i k t},
\end{aligned}
$$

where $v_{k}=\bar{v}_{k}, f_{k}=\bar{f}_{k}$. Multiplying (4) by $e^{-i k t} / 2 \pi$ and integrating, we have

$$
\frac{1}{2 \pi} \int_{0}^{2 \pi} e^{-i k t} L_{\epsilon}[v] d t=\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} f(v(t)) e^{-i k t} d t
$$

or

$$
v_{k} q_{\epsilon}(i k)=\epsilon \epsilon_{k} .
$$

Since $\left|q_{\epsilon}(i k) / \epsilon\right|$ is bounded away from zero for small $\epsilon$, then we can solve for $v_{\boldsymbol{k}}$;

$$
v_{k}=\frac{\epsilon f_{k}}{q_{\epsilon}(i k)},
$$

[^2]and, therefore, $v$ is the convolution of $f$ and $K^{*}$ given by (15); i.e.,
\[

$$
\begin{equation*}
v(t)=\frac{1}{2 \pi} \int_{0}^{2 \pi} K^{*}(t-s) f(v(s)) d s \tag{16}
\end{equation*}
$$

\]

To prove sufficiency, let $v$ be an $H_{1}$ solution of (16). Then, $v$ is continuously differentiable for the following reasons. First, $v \in H_{1} \Rightarrow f(v) \in H_{1}$ since $f$ is continuously differentiable. Hence, $\sum_{k}\left|i k f_{k}\right|^{2}<\infty$. Differentiating (16) twice, we have

$$
v^{\prime \prime}(t)=\frac{1}{2 \pi} \int_{0}^{2 \pi} \sum_{k} \frac{-\epsilon k^{2} \exp (i k(t-s))}{q_{\epsilon}(i k)} f(v(s)) d s
$$

which is in $H_{0}$ since for large $k,\left|1 / q_{\epsilon}(i k)\right|=O(1 /|k|)$, and hence,

$$
\left\|v^{\prime \prime}\right\|_{0}^{2}=\sum_{k}\left|\frac{\epsilon k^{2} f_{k}}{q_{\epsilon}(i k)}\right|^{2}<c_{1} \sum\left|k f_{k}\right|^{2}<\infty
$$

provided $\epsilon$ is small. Thus, $v(t) \in H_{2}$, which implies that $v(t)$ is continuously differentiable. Note that by continuing we could get that $v \in H_{k+1}$ if $f \in C_{k}$.

Hence, we may operate with $L_{\epsilon}$ on $v$ which yields

$$
\begin{aligned}
L_{\epsilon}[v] & =\frac{1}{2 \pi} \int_{0}^{2 \pi} \sum_{k} \frac{\epsilon}{q_{\epsilon}(i k)} L_{\epsilon}[\exp (i k(t-s))] f(v(s)) d s \\
& =\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} \sum_{k} \exp (i k(t-s)) f(v(s)) d s \\
& =\epsilon f(v(t))
\end{aligned}
$$

i.e., $v$ is a solution of (4).

We now rewrite Eq. (16) as three integral equations. For any real periodic function $v(t)$ of periodic $2 \pi$, let

$$
\begin{equation*}
v=a e^{i t}+\bar{a} e^{-i t}+u(t) \tag{17}
\end{equation*}
$$

where $a$ is some complex number and $u$ is orthogonal to $e^{ \pm i t}$, i.e., $(1 / 2 \pi) \int_{0}^{2 \pi} u(t) e^{ \pm i t} d t=0$. We may assume that $a$ is real since $v(t)$ is a solution if and only if $v(t+\phi)$ is also a solution. Thus, equation (16) can be decomposed into the following simultaneous integral equations,

$$
\begin{align*}
a x & =\frac{1}{2 \pi} \int_{0}^{2 \pi} f(v(t)) \cos t d t  \tag{18}\\
a y & =-\frac{1}{2 \pi} \int_{0}^{2 \pi} f(v(t)) \sin t d t  \tag{19}\\
u(t) & =\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} K(t-s) f(v(s)) d s \tag{20}
\end{align*}
$$

where

$$
\begin{equation*}
K(t-s)=\sum_{k \neq \neq 1} \frac{\exp (i k(t-s))}{q_{\epsilon}(i k)} \tag{21}
\end{equation*}
$$

and $v$ is given by (17) where $a$ is real. Here, $x+i y \equiv q_{\epsilon}(i) / \epsilon$, as before. The problem is to prove for small $\epsilon$ the existence of a solution $(a, u(t), \omega)$. This will be done in two
steps. First, we obtain an $H_{1}$ solution, $u\left(t, a, \omega_{1}\right)$, of Eq. (20) where $\omega=\omega_{0}+\epsilon \omega_{1}$, $a$ and $\omega_{1}$ are considered free parameters, $\omega_{1} \geq 0$, and $\left|a-a^{*}\right|<\frac{1}{2}\left|a^{*}\right|$. Then, we use the implicit function theorem to prove the existence of $a, \omega_{1}$ such that Eqs. (18) and (19) are also satisfied.

The existence $u\left(t a, \omega_{1}\right) \in H_{1}$ of (20) will be shown using the following iteration

$$
\begin{gather*}
u_{0}\left(t, a, \omega_{1}\right)=0 \\
u_{n+1}=\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} K(t-s) f\left(2 a \cos s+u_{n}(s)\right) d s, \quad n=0,1, \cdots \tag{22}
\end{gather*}
$$

The proof is by induction with the following induction hypotheses for $n=1,2,3, \cdots$,
(a) $\max _{0 \leq t \leq 2 \pi}\left|u_{n}(t)\right|<O(\epsilon)$ (independent of $n$ ),
(b)* $\left\|u_{n+1}-u_{n}\right\|_{0,1}^{2}<\frac{1}{4}\left\|u_{n}-u_{n-1}\right\|_{0}^{2}$.

The first hypothesis guarantees that $v_{n}(t)=2 a \cos t+u_{n}(t)$ is bounded in the maximum norm; i.e., $\max _{0 \leq t \leq 2 \pi}\left|v_{n}(t)\right|<2|a|+O(\epsilon)<4\left|a^{*}\right|$; and hence, by assumption, $\left|f^{\prime}\left(v_{n}\right)\right|<\nu$. The second hypothesis implies the convergence of the sequence $u_{n}$ in $H_{1}$ since

$$
\left\|u_{n+1}-u_{n}\right\|_{0,1} \leq\left(\frac{1}{2}\right)^{n-1}\left\|u_{2}-u_{1}\right\|_{0}
$$

or

$$
\left\|u_{n}-u_{m}\right\|_{0,1}<2\left\|u_{m+1}-u_{m}\right\|_{0} \leq\left(\frac{1}{2}\right)^{m-2}\left\|u_{2}-u_{1}\right\|_{0}
$$

which approaches zero as $m, n \rightarrow \infty$.
We use the following
Lemma 2. Let $\mathfrak{K} \phi=(1 / 2 \pi) \int_{0}^{2 \pi} K(t-s) \phi(s) d s$ where

$$
K(t-s)=\sum_{k \neq \pm 1} \frac{e^{i k(t-s)}}{q_{\epsilon}(i k)}
$$

and $\phi$ is $2 \pi$-periodic. Then

$$
\|\Re \phi\|_{0,1}^{2} \leq c^{2}\|\phi\|_{0}^{2}
$$

where

$$
c=\max _{k \neq \pm 1}\left|\frac{i k}{q_{\epsilon}(i k)}\right|<\infty
$$

Proof: If $\phi_{k}$ denote the Fourier coefficients of $\phi$, then by Parseval's equality,

$$
\|\mathcal{K} \phi\|_{0}^{2}=\sum_{k \neq \pm 1}\left|\frac{\phi_{k}}{q_{\epsilon}(i k)}\right|^{2} \leq c_{0}^{2}\|\phi\|_{0}^{2},
$$

where $c_{0}=\max _{k \neq \pm 1}\left|1 / q_{\epsilon}(i k)\right|$. Similarly,

$$
\|\Re \phi\|_{1}^{2}=\sum_{k \neq \neq 1}\left|\frac{i k \phi_{k}}{q_{\epsilon}(i k)}\right|^{2} \leq c^{2}\|\phi\|_{0}^{2},
$$

where $c=\max _{k \neq \pm 1}\left|i k / q_{\epsilon}(i k)\right| \geq c_{0}$. It remains to be proved that $c$ is finite, but this follows since $\left|q_{\epsilon}(i k)\right| \geq \eta>0$ for $\epsilon$ small, $k \neq \pm 1$, and $1 /\left|q_{\epsilon}(i k)\right|=O\left(|k|^{-1}\right),|k| \rightarrow \infty$. This completes the proof of Lemma 2.

[^3]To prove (a) for $n=1$, we use the fact that

$$
\begin{equation*}
\max _{0 \leq t \leq 2 \pi}|w(t)| \leq(2 \pi)^{3 / 2}\left(\|w\|_{0}+\|w\|_{1}\right) \tag{23}
\end{equation*}
$$

From Lemma 2 and (22) we have

$$
\left\|u_{1}\right\|_{0,1} \leq \epsilon c\|f(2 a \cos t)\|_{0}
$$

and since we assume $\left|a-a^{*}\right|<\frac{1}{2}\left|a^{*}\right|$, then $|2 a \cos t|<3\left|a^{*}\right|,\left|f^{\prime}\right|<\nu$, and hence (since $f(0)=0)$,

$$
\left\|u_{1}\right\|_{0,1} \leq 3 \epsilon c \nu\left|a^{*}\right|
$$

Thus, by (23),

$$
\max _{0 \leq t \leq 2 \pi}\left|u_{1}(t)\right| \leq O(\epsilon)
$$

proving (a) for $n=1$.
To prove (b) for $n=1$, we compute

$$
u_{2}-u_{1}=\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} K(t-s)\left[f\left(v_{1}(s)-f\left(v_{0}(s)\right)\right] d s\right.
$$

where $v_{n}(s)=2 a \cos s+u_{n}(s)$. By Lemma 2 and the fact that $\left|v_{1}\right|<4\left|a^{*}\right|,\left|v_{0}\right|<4\left|a^{*}\right|$, we have

$$
\left\|u_{2}-u_{1}\right\|_{0,1}^{2} \leq(\epsilon C \nu)^{2}\left\|u_{1}-u_{0}\right\|_{0}^{2}<\frac{1}{4}\left\|u_{1}-u_{0}\right\|_{0}^{2}
$$

for $\epsilon<\frac{1}{2} c \nu$ proving (b) for $n=1$.
Now assume (a) and (b) hold for $n \leq N-1$. Then, by (b)

$$
\left\|u_{n}-u_{n-1}\right\|_{0,1}^{2} \leq \frac{1}{4}\left\|u_{n-1}-u_{n-2}\right\|_{0}^{2}, \quad n=2,3, \cdots, N
$$

and by (23)

$$
\begin{aligned}
\max _{0 \leq t \leq 2 \pi}\left|u_{N}(t)\right| & \leq(2 \pi)^{3 / 2}\left(\left\|u_{N}\right\|_{0}+\left\|u_{N}\right\|_{1}\right) \\
& \leq(2 \pi)^{3 / 2} \sum_{n=1}^{N}\left(\left\|u_{n}-u_{n-1}\right\|_{0}+\left\|u_{n}-u_{n-1}\right\|_{1}\right) \\
& \leq(2 \pi)^{3 / 2}\left[2 \sum_{n=2}^{N}(1 / 2)^{n-1}\left\|u_{1}\right\|_{0}+\left\|u_{1}\right\|_{0}+\left\|u_{1}\right\|_{1}\right] \\
& \leq 4(2 \pi)^{3 / 2} 3 \epsilon \nu\left|a^{*}\right| \\
& \leq O(\epsilon)
\end{aligned}
$$

Thus, (a) holds for $n=N$.
Using (a) we have $\left|v_{N}(t)\right| \leq 4\left|a^{*}\right|$ which gives us that $\left|f^{\prime}\left(v_{n}\right)\right|<\nu$. Then by Lemma 2

$$
\begin{aligned}
\left\|u_{N+1}-u_{N}\right\|_{0,1}^{2} & \leq(\epsilon c)^{2}\left\|f\left(v_{N}\right)-f\left(v_{N-1}\right)\right\|_{0}^{2} \\
& \leq(\epsilon c \nu)^{2}\left\|u_{N}-u_{N-1}\right\|_{0}^{2} \\
& \leq \frac{1}{4}\left\|u_{N}-u_{N-1}\right\|_{0}^{2}
\end{aligned}
$$

proving (b) for $n=N$. By induction (a) and (b) hold for all $n$ proving the convergence of $u_{n}$ in $H_{1}$.

The last part of the proof consists of proving that for $\epsilon$ small there exist $a(\epsilon), \omega_{1}(\epsilon)$ such that Eqs. (18) and (19) hold. The proof uses the implicit function theorem.

Define

$$
F\left(a, \omega_{1}, \epsilon\right) \equiv a x\left(\omega_{1}, \epsilon\right)-\frac{1}{2 \pi} \int_{0}^{2 \pi} f\left(2 a \cos t+u^{*}\left(t, a, \omega_{1}, \epsilon\right)\right) \cos t d t
$$

and

$$
G\left(a, \omega_{1}, \epsilon\right) \equiv a y\left(\omega_{1}, \epsilon\right)+\frac{1}{2 \pi} \int_{0}^{2 \pi} f\left(2 a \cos t+u^{*}\left(t, a, \omega_{1}, \epsilon\right)\right) \sin t d t
$$

where $u^{*}\left(t, a, \omega_{1}, \epsilon\right)$ is the solution of Eq. (16). Equations (18) and (19) are simply

$$
\begin{aligned}
& F\left(a, \omega_{1}, \epsilon\right)=0 \\
& G\left(a, \omega_{1}, \epsilon\right)=0
\end{aligned}
$$

For $\epsilon=0$, we have the solution

$$
\begin{align*}
a(0) & =a^{*}  \tag{24}\\
\omega_{1}(0) & =\frac{\omega_{n}\left(\omega_{0}^{2}+\gamma^{2}\right)}{\gamma(\gamma+\beta)+h \beta\left(\gamma^{2}+\omega_{0}^{2}\right)}
\end{align*}
$$

This follows since $u^{*}\left(t, a, \omega_{1}, 0\right)=0$, so that

$$
F\left(a^{*}, \omega_{1}, 0\right)=a^{*} x_{0}-\frac{1}{2 \pi} \int_{0}^{2 \pi} f\left(2 a^{*} \cos t\right) \cos t d t=0
$$

by (10). Similarly,

$$
G\left(a^{*}, \omega_{1}, 0\right)=a^{*} y_{0}+\frac{1}{2 \pi} \int_{0}^{2 \pi} f\left(2 a^{*} \cos t\right) \sin t d t=a^{*} y_{0}
$$

where we have used the fact that $f\left(2 a^{*} \cos t\right)$ is even function of $t$. With the choice of $\omega_{1}$ given by (24) and using (13) we see that $y_{0}=0$.

It remains to be shown that

$$
\left|\begin{array}{ll}
\frac{\partial F}{\partial a} & \frac{\partial F}{\partial \omega_{1}}  \tag{25}\\
\frac{\partial G}{\partial a} & \frac{\partial G}{\partial \omega_{1}}
\end{array}\right|_{a=a^{*} ; \omega_{1}-\omega_{1}(0) ; \in=0} \neq 0
$$

However, there still exists the question whether these derivatives exist. The argument for this will be omitted since it provides nothing interesting. The basic argument consists of differentiating Eq. (20) with respect to $a$ and $\omega_{1}$ and showing by the contracting map theorem that there exist unique solutions of the resulting equations. Then one can show that the difference quotients

$$
\frac{u^{*}\left(t, a+\Delta a, \omega_{1}, \epsilon\right)-u^{*}\left(t, a, \omega_{1}, \epsilon\right)}{\Delta a}
$$

and

$$
\frac{u^{*}\left(t, a, \omega_{1}+\Delta \omega_{1}, \epsilon\right)-u^{*}\left(t, a, \omega_{1}, \epsilon\right)}{\Delta \omega_{1}}
$$

are uniformly bounded in $H_{1}$ and equicontinuous, and, therefore, have a convergent subsequence. However, the limit must satisfy the differentiated equation and hence is unique.

To prove (25), we note that

$$
\left.\frac{\partial u^{*}}{\partial a}\right|_{\epsilon=0}=\left.\frac{\partial u^{*}}{\partial \omega_{1}}\right|_{\epsilon=0}=0
$$

since

$$
u^{*}(t)=\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} K(t-s) f\left(2 a \cos s+u^{*}(s)\right) d s
$$

and

$$
\left.\frac{\partial K}{\partial \omega_{1}}\right|_{\epsilon=0}=0
$$

We compute

$$
\begin{align*}
& \left.\quad \frac{\partial F}{\partial a}\right|_{a=a^{*} ; \omega_{2}=\omega_{1}(0) ; \in=0}=x_{0}-\frac{1}{2 \pi} \int_{0}^{2 \pi} f^{\prime}\left(2 a^{*} \cos t\right) 2 \cos ^{2} t d t  \tag{26}\\
& \begin{aligned}
&\left.\frac{\partial G}{\partial \omega_{1}}\right|_{a=a^{*} ; \omega_{1}=\omega_{1}(0) ; \epsilon=0}=a^{*} \frac{\omega_{0}}{\omega_{1}(0)}, \\
&\left.\frac{\partial G}{\partial a}\right|_{a=a^{*} ; \omega_{1}=\omega_{1}(0) ; \epsilon=0}=y_{0}+\frac{1}{2 \pi} \int_{0}^{2 \pi} f^{\prime}\left(2 a^{*} \cos t\right) 2 \cos t \sin t d t=0 .
\end{aligned}
\end{align*}
$$

Since (26) is not zero by assumption and $a^{*} \omega_{0} / \omega_{1}(0) \neq 0$, we have that (25) is also not zero. By the implicit function theorem for small $\epsilon$ there exist unique functions $\omega_{1}=\omega_{1}(\epsilon)$ and $a=a(\epsilon)$ such that

$$
\begin{aligned}
& F\left(a(\epsilon), \omega_{1}(\epsilon), \epsilon\right) \equiv 0, \\
& G\left(a(\epsilon), \omega_{1}(\epsilon), \epsilon\right) \equiv 0,
\end{aligned}
$$

and $a(0)=a^{*}$. This completes the proof of the theorem.
Acknowledgment. The author would like to thank Professor Jürgen Moser of the Courant Institute of Mathematical Sciences, New York University, for his encouragement and his many constructive suggestions.

## References

1. R. Bellman and K. L. Cooke, Differential-difference equations, Academic Press, New York, 1963.
2. N. Krasovskii, On periodic solutions of differential equations involving a time lag, Dokl. Acad. Nauk (N. S.), 114 252-255 (1957).
3. N. Shimanov, Almost periodic solutions in nonlinear systems with retardation, Dokl. Acad. Nauk, S. S. S. R., 125 1203-1206 (1959).
4. N. Shimanov, On the vibration theory of quasilinear systems with lags, Prikl. Mat. Meh. 23 836-844 (1959); TPMM, 1198-1208.
5. J. K. Hale, Linear functional-differential equations with constant coefficients, Contributions to Differential Equations (2), 291-317 (1963).
6. R. K. Brayton, Nonlinear oscillations in a distributed network. To appear in a forthcoming issue of Quart. of Applied Math.

[^0]:    *Received November 5, 1965; revised manuscript received March 4, 1966. The results reported in this paper were obtained in the couse of research jointly sponsored by the Air Force Office of Scientific Research (Contract AF 49(638)-1139) and IBM.

[^1]:    *By solution, we mean a continuously differentiable function $v(t)$ which satisfies (4) point-wise.

[^2]:    *The spaces $H_{0}$ and $H_{1}$ denote Hilbert spaces with metrics $\|w\|_{0}^{2}=(1 / 2 \pi) \int_{0}^{2 \pi} w^{2} d t$ and $\|w\|_{0+1}^{2}=$ $\|w\|_{0}^{2}+\|w\|_{1}^{2}$, respectively, where the notation $\|w\|_{1}^{2}$ will be used for the pseudo-metric ( $1 / 2 \pi$ ) $\int_{0}^{2 \pi}$ $(d w / d t)^{2} d t$.

[^3]:    *The notation $\|w\|_{0,1}^{2}<g$ denotes $\|w\|_{0}^{2}<g$ and $\|w\|_{1}^{2}<g$.

