

APPLICATIONS OF HOMOTOPY IN SHEAF THEORY

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ABSTRACT. Various mapping theorems for sheaf cohomology are obtained, where coefficients are in locally constant sheaves or limits of locally constant sheaves. Applications are made to the continuity of sheaf cohomology on homotopy-systems. A generalization of the Alexander-Čech cohomology continuity theorem is an immediate consequence.

1. Notation. The category of sheaves (of some algebraic structure) of a fixed (always Hausdorff) space X will be denoted by \mathfrak{A}_X . The (full) subcategory of \mathfrak{A}_X of locally constant sheaves (or limits of locally constant sheaves) on X will be denoted by \mathfrak{A}'_X (\mathfrak{A}^*_X). For general definitions in sheaf theory see [1, Chapter 17] and [2]. All maps are assumed to be continuous.

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2. Applications in sheaf cohomology. If $f: X \rightarrow Y$ is a homotopy equivalence with homotopy inverse g , $\mathcal{A} \in \mathfrak{A}'_Y$ with respect to the open cover G of Y , and $F = f^{-1}(G)$, then f is an (F, G) -homotopy equivalence (relative to \mathcal{A}) iff $fg \simeq 1_Y$ by a G -homotopy and $gf \simeq 1_X$ by a F -homotopy.

THEOREM 1. *If $\mathcal{A} \in \mathfrak{A}'_Y$ with respect to the cover G of Y , $f: X \rightarrow Y$ is an (F, G) -homotopy equivalence, and X and Y are compact, then there exists a sheaf $\mathcal{B} \in \mathfrak{A}'_X$ such that $H_c^*(X, \mathcal{B}) \approx H_c^*(Y, \mathcal{A})$.*

Let $\mathcal{B} = f^*\mathcal{A}$ and $(f, f^*): S(Y, \mathcal{A}) \rightarrow S(X, \mathcal{B})$ be the homomorphism defined by $(f, f^*)(s)(x) = f_x^*s f(x)$, for all $s \in S(Y, \mathcal{A})$, where $\{f_x^*\}$ is the inverse image cohomomorphism.

Likewise, if g is the homotopy inverse of f , define a homomorphism $(g, g^*): S(X, \mathcal{B}) \rightarrow S(Y, \mathcal{A})$. This map is well defined since locally constant

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sheaves behave like locally constant bundles with respect to homotopic maps of the base space ([5, p. 53], [4]). Thus $g^*f^*\mathcal{A} \approx \mathcal{A}$ and $f^*g^*f^*\mathcal{A} \approx f^*\mathcal{A}$.

The map (f, f^*) is onto, since $\text{Im} f \cap U \neq \emptyset$ for all $U \in G$ by the (F, G) -homotopy equivalence property of f (similarly for (g, g^*)). Note that stalkwise the maps are isomorphisms. Thus $S(X, f^*\mathcal{A}) \approx S(Y, \mathcal{A})$.

Similarly, for serrations [1, p. 481], $S(X, \mathcal{T}^0 f^*\mathcal{A}) \approx S(Y, \mathcal{T}^0 \mathcal{A})$, and by iteration $S(X, \mathcal{T}^* f^*\mathcal{A}) \approx S(Y, \mathcal{T}^* \mathcal{A})$, or $H_c^*(X, f^*\mathcal{A}) \approx H_c^*(Y, \mathcal{A})$.

An immediate application of Theorem 1 to sheaves in \mathfrak{U}_Y^* is possible under somewhat restrictive assumptions.

COROLLARY 2. *Let $\{Y_\alpha, \varphi_\alpha^\beta\}_\Lambda$ be an inverse system of compact spaces, $\{\mathcal{A}_\alpha, \Phi_\alpha^\beta\}_\Lambda$ a direct system of locally constant sheaves on $\{Y_\alpha, \varphi_\alpha^\beta\}_\Lambda$ with respect to covers $\{G_\alpha\}_\Lambda$, and let $\{X_\alpha, \psi_\alpha^\beta\}_\Lambda$ be an inverse system of compact spaces with $F = \{f_\alpha: X_\alpha \rightarrow Y_\alpha \mid f_\alpha \text{ is an } (F_\alpha, G_\alpha)\text{-homotopy equivalence}\}$ a map of the systems. Let $Y = \text{proj lim } Y_\alpha$, $X = \text{proj lim } X_\alpha$, and $\mathcal{A} = \text{inj lim } \varphi_\alpha^* \mathcal{A}_\alpha$ (where $\varphi_\alpha: X \rightarrow X_\alpha$). Then there exists a sheaf $\mathcal{B} \in \mathfrak{U}_X^*$ such that $H_c^*(X, \mathcal{B}) \approx H_c^*(Y, \mathcal{A})$.*

By Theorem 1 one has $H_c^*(X_\alpha, f_\alpha^* \mathcal{A}_\alpha) \approx H_c^*(Y_\alpha, \mathcal{A}_\alpha)$ for all $\alpha \in \Lambda$. By continuity [2, pp. 69–72], $\text{inj lim } H_c^*(Y_\alpha, \mathcal{A}_\alpha) \approx H_c^*(Y, \mathcal{A})$ and $\text{inj lim } H_c^*(X_\alpha, f_\alpha^* \mathcal{A}_\alpha) \approx H_c^*(X, f^* \mathcal{A})$, where $f^* \mathcal{A} = \text{inj lim } \psi_\alpha^* f_\alpha^* \mathcal{A}_\alpha \approx \text{inj lim } f^* \varphi_\alpha^* \mathcal{A}_\alpha$. Let $\mathcal{B} = f^* \mathcal{A}$ and the result follows.

An existence theorem which satisfies the hypothesis of Corollary 2 for sheaves in \mathfrak{U}_Y^* is established by the following theorem.

THEOREM 3. *Let $\mathcal{A} \in \mathfrak{U}_Y^*$, $f: X \rightarrow Y$ be an (F_α, G_α) -homotopy equivalence for all $\alpha \in \Lambda$, where $\mathcal{A} = \text{inj lim } \mathcal{A}_\alpha$. Suppose X and Y are compact spaces. Then there exists a sheaf $\mathcal{B} \in \mathfrak{U}_X$ such that $H_c^*(Y, \mathcal{A}) \approx H_c^*(X, \mathcal{B})$.*

Imbed Y in $\prod_{\alpha \in \Lambda} I_\alpha$, where $\Lambda = I^Y$, and construct an inverse system of finite polyhedra $\{Y_\alpha, \varphi_\alpha^\beta\}_\Lambda$ such that $Y = \text{proj lim } Y_\alpha$ [3, p. 284].

Let Z_{φ_α} be the mapping cylinder of the projection map $\varphi_\alpha: Y \rightarrow Y_\alpha$ (recall $Z_{\varphi_\alpha} \simeq Y_\alpha$). Thus $\{Z_{\varphi_\alpha}, \tilde{\varphi}_\alpha^\beta\}_\Lambda$ is an inverse system, where $\tilde{\varphi}_\alpha^\beta$ is induced by φ_α^β , and $\text{proj lim } Z_{\varphi_\alpha} = Y \times I \simeq Y$.

Let $\mathcal{A}_\alpha \times [0, 1)$ be the sheaf on $Y \times [0, 1)$ such that $(\mathcal{A}_\alpha \times [0, 1))_{(x,t)} = (\mathcal{A}_\alpha)_x$ for all $(x, t) \in Y \times [0, 1)$. Since $Y \times [0, 1)$ is locally closed in Z_{φ_α} , extend $\mathcal{A}_\alpha \times [0, 1)$ to Z_{φ_α} by zero and denote this sheaf by $\tilde{\mathcal{A}}_\alpha$. Thus $\text{inj lim } \tilde{\mathcal{A}}_\alpha = \tilde{\mathcal{A}} = (\mathcal{A} \times [0, 1)) \cup \theta$.

Carry out a similar construction on X and the system $\{f^* \mathcal{A}_\alpha\}$.

Clearly, $H_c^*(Y, \mathcal{A}) \approx H_c^*(Y \times [0, 1), \mathcal{A} \times [0, 1)) \approx H_c^*(Y \times I, \tilde{\mathcal{A}})$. Similarly for X and $(f^* \mathcal{A}_\alpha) \simeq \text{inj lim } \tilde{f}^* \tilde{\mathcal{A}}_\alpha$.

By continuity [2, pp. 69–72],

$$H_c^*(Y, \mathcal{A}) \approx H_c^*(Y \times I, \tilde{\mathcal{A}}) \approx \text{inj lim } H_c^*(Z_{\varphi_\alpha}, \tilde{\mathcal{A}}_\alpha),$$

and

$$H_c^*(X, f^*\mathcal{A}) \approx H_c^*(X \times I, (f^*\mathcal{A})^\sim) \approx \text{inj lim } H_c^*(Z_{\psi_\alpha}, \tilde{f}^*\tilde{\mathcal{A}}_\alpha)$$

where \tilde{f} is the extension of f to Z_{ψ_α} .

By Theorem 1, $H_c^*(Z_{\varphi_\alpha}, \tilde{\mathcal{A}}_\alpha) \approx H_c^*(Z_{\varphi_\alpha}, \tilde{f}^*\tilde{\mathcal{A}}_\alpha)$ for all $\alpha \in \Lambda$, since f is an (F_α, G_α) -homotopy equivalence (and thus \tilde{f} is an $(\tilde{F}_\alpha, \tilde{G}_\alpha)$ -homotopy equivalence, where \tilde{G}_α is the cover $G_\alpha \times [0, 1) \cup Y_\alpha$). Thus $H_c^*(Y, \mathcal{A}) \approx H_c^*(X, f^*\mathcal{A})$, and $\mathcal{B} = f^*\mathcal{A}$.

3. Continuity theorems. The introduction of homotopy-systems in the above setting precipitates the following results on continuity (see [4] for basic definitions and properties of homotopy-systems).

An inverse system of spaces $\{X_\alpha, \varphi_\alpha^\beta\}_\Lambda$ is called a *homotopy-inverse system* (F_α -homotopy-inverse system) iff whenever $\alpha, \beta, \gamma \in \Lambda$ and $\alpha < \beta < \gamma$, then $\varphi_\alpha^\beta \varphi_\beta^\gamma \simeq \varphi_\alpha^\gamma$ ($\varphi_\alpha^\beta \varphi_\beta^\gamma \simeq \varphi_\alpha^\gamma$ by a F_α -homotopy for some cover F_α of X_α).

THEOREM 4. *If $\{X_\alpha, \varphi_\alpha^\beta\}_\Lambda$ is a F_α -homotopy-inverse system of locally path connected compact spaces with respect to covers $\{F_\alpha\}_\Lambda$ determined by some system $\{\mathcal{A}_\alpha, \Phi_{\beta\gamma}^\alpha\}$ of locally constant sheaves on $\{X_\alpha, \varphi_\alpha^\beta\}_\Lambda$ (where $\Phi_{\beta\gamma}^\alpha$ are φ_α^β -cohomorphisms), then $H_c^*(X, \mathcal{A}) = H_c^*(\text{h-proj lim } X_\alpha, \text{inj lim } \varphi_\alpha^* \mathcal{A}_\alpha) \approx \text{inj lim } H_c^*(X_\alpha, \mathcal{A}_\alpha)$.*

The homotopy-inverse limit space, $X = \text{h-proj lim } X_\alpha$, is compact [4], and if $\varphi_\alpha: X \rightarrow X_\alpha$ is the projection map, then $\varphi_\alpha^* \mathcal{A}_\alpha$ is a locally constant sheaf on X with respect to the cover $\varphi_\alpha^{-1}(F_\alpha)$. If $\mathcal{A} = \text{inj lim } \varphi_\alpha^* \mathcal{A}_\alpha$, then $\text{inj lim } H_c^*(X, \varphi_\alpha^* \mathcal{A}_\alpha) \approx H_c^*(X, \mathcal{A})$. In view of the fact that the sheaves $\{\mathcal{A}_\alpha\}$ and $\{\varphi_\alpha^* \mathcal{A}_\alpha\}$ are locally constant, the behavior of the direct limit functor on $\{H_c^*(X_\alpha, \mathcal{A}_\alpha)\}$ is identical to the usual situation and the result follows.

The following corollary is immediate.

COROLLARY 5. *If X is compact and \mathcal{A} is the limit of sheaves in \mathfrak{U}_X^* , then $H_c^*(X, \mathcal{A})$ may be expressed as a doubly iterated limit of cohomologies of spaces of the homotopy type of polyhedra with coefficients in locally constant sheaves.*

If constant sheaves are present in Theorem 4 the F_α -homotopy condition in Theorem 4 may be weakened to give the following generalization of the Alexander-Čech continuity theorem [1, p. 168].

COROLLARY 6. *If $\{X_\alpha, \varphi_\alpha^\beta\}_\Lambda$ is a homotopy-inverse system of locally path connected compact spaces, then $H_c^*(\text{h-proj lim } X_\alpha, R) \approx \text{inj lim } H_c^*(X_\alpha, R)$.*

An analogous result may be obtained for Čech homology.

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