TOPOLOGY OF QUATERNIONIC MANIFOLDS

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We give here a quaternionic analogue (Theorem 4) of the Hodge decomposition theorem [2, p. 26] for a Riemannian manifold with holonomy group contained in $Sp(n) \times Sp(1)$. Applying Chern's theorem in [1] (also [3]), we obtain some consequences on Betti numbers (Theorem 5).

Let K^n denote the *n*-dimensional vector space over the field K of quaternions, with the inner product

$$(\boldsymbol{p},\boldsymbol{q}) = \frac{1}{2} \sum_{i=1}^{n} (p_i \bar{q}_i + q_i \bar{p}_i),$$

where

$$p = (p_1, \dots, p_n), \qquad q = (q_1, \dots, q_n) \text{ and}$$

$$p_i = p_i^0 + p_i^1 i + p_i^2 j + p_i^3 k,$$

$$q_i = q_i^0 + q_i^1 i + q_i^2 j + q_i^3 k$$

are quaternions.

Let Sp(n) be the set of all endomorphisms, A, of K^n , satisfying the identity (Ap, Aq) = (p, q). Sp(n) is the set of all $n \times n$ matrices preserving the inner product. Then Sp(1) is the set of all unit quaternions. We define the action of $\text{Sp}(n) \times \text{Sp}(1)$ on K^n as follows:

 $(A, \lambda)\mathbf{p} = A\mathbf{p}\lambda, \text{ for } (A, \lambda) \in \operatorname{Sp}(n) \times \operatorname{Sp}(1),$

i.e., we multiply p on the left by the matrix A and on the right by the unit quaternion λ .

DEFINITION. We define three skew symmetric bilinear forms Ω_I , Ω_J and Ω_K on K^n as follows:

$$egin{aligned} \Omega_I(oldsymbol{p},oldsymbol{q}) &= (oldsymbol{p}i,oldsymbol{q}), \ \Omega_J(oldsymbol{p},oldsymbol{q}) &= (oldsymbol{p}j,oldsymbol{q}) ext{ and } \ \Omega_K(oldsymbol{p},oldsymbol{q}) &= (oldsymbol{p}k,oldsymbol{q}). \end{aligned}$$

Note that Ω_I , Ω_J and Ω_K may be thought of as exterior 2-forms of K^n considered as a 4n-dimensional real vector space.

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DEFINITION. We define an exterior 4-form Ω on K^n by

 $\Omega = \Omega_I \wedge \Omega_I + \Omega_J \wedge \Omega_J + \Omega_K \wedge \Omega_K.$

THEOREM 1. Ω is invariant under the action of $Sp(n) \times Sp(1)$.

THEOREM 2. $\Omega^n = \Omega \wedge \Omega \wedge \cdots \wedge \Omega$ (*n* times) $\neq 0$.

DEFINITION. A 4*n*-dimensional Riemannian manifold M is called a *quaternionic manifold* if its holonomy group is a subgroup of $Sp(n) \times Sp(1)$.

If M is a quaternionic manifold of dimension 4n, then, by Theorems 1 and 2, we have a differential 4-form Ω on M of maximal rank (i.e., $\Omega^n \neq 0$) which is parallel. Hence, Ω is a harmonic form. From the fact that $\Omega^n \neq 0$, we have

THEOREM 3. If B_i denotes the *i*th Betti number of a quaternionic manifold M of dimension 4n, then we have $B_{4i} \neq 0$ for $i = 0, 1, \dots, n$.

We define the operator * which sends a *p*-form into a (4n-p)-form in the usual way.

DEFINITION. Define two operators L and Λ on the differential forms by

$$Lw = \Omega \wedge w, \qquad \Lambda w = *(\Omega \wedge *w).$$

A differential form w is called *effective* if $\Lambda w = 0$.

THEOREM 4. Let w be a p-form; then

$$w = w_{e}^{p} + Lw_{e}^{p-4} + \cdots + L^{r}w_{e}^{p-4r}, \text{ for } p \leq n,$$

where w_e^k is an effective k-form, and $r = \lfloor p/4 \rfloor$.

From Theorem 4, it follows that L sending p-forms into (p+4)-forms is 1-1 for $p \leq n-4$.

THEOREM 5. We have an increasing sequence of Betti numbers,

 $B_i \leq B_{i+4} \leq \cdots \leq B_{i+4r}$, for $i + 4r \leq n$, i = 0, 1, 2 or 3.

Bibliography

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