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Iryna Uleychuk* (mathacadem-Kiev@ukr.net), Ukr,76006,Ivano-Francovsk,st.:24 Serpny,30,
76006 Ivano-Frankovsk, Ukraine. *The solution differential systems with delay and with commutative matrixes*

$$\dot{x}(t) = Ax(t) + B(t - \tau) \quad (1)$$

$x(t) \in R^n, t \geq 0, \tau = const.$

DEFINITION 1. Delay exponential of matrix B is matrix function e_τ^{Bt} that has a form

$$e_\tau^{Bt} = \begin{cases} \theta, & \text{at } -\infty < t < -\tau; \\ I, & \text{at } -\tau \leq t < 0; \\ I + B\frac{t}{1!} + B^2\frac{(t-\tau)^2}{2!} + \dots + B^k\frac{(t-(k-1)\tau)^k}{k!}, & \text{at } (k-1)\tau \leq t < k\tau. \end{cases}$$

$k = 0, 1, 2, \dots$, where θ is zero matrix.

THEOREM 1. Let $AB = BA$ of the system (1) is true. Then the solution Cauchy problem for system (1) has a form

$$x(t) = e^{A(t-\tau)} e_\tau^{B_1(t-\tau)} \varphi(-\tau) + \int_{-\tau}^0 e^{A(t-\tau-s)} e_\tau^{B_1(t-\tau-s)} e^{A\tau} [\varphi'(s) - A\varphi(s)] ds$$

$$\dot{x}(t) = Ax(t) + B(t - \tau) + f(t) \quad (2)$$

THEOREM 3. The solution $\bar{x}(t)$ of nonhomogeneous system (2) with zero initial conditions has form $\bar{x}(t) = \int_0^t e^{A(t-\tau-s)} e_\tau^{B_1(t-\tau-s)} f(s) ds, t \geq 0.$

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